

DATA SHEET

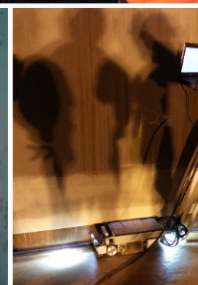
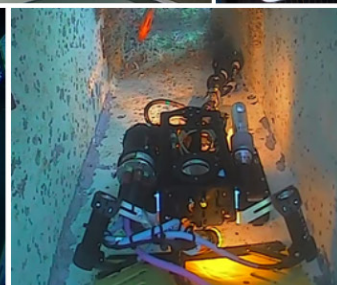
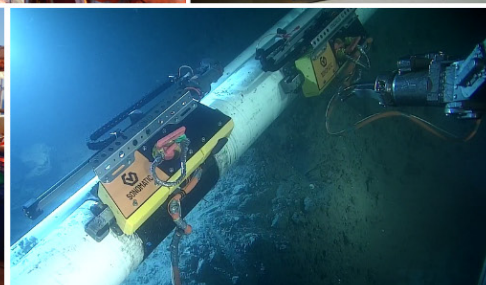
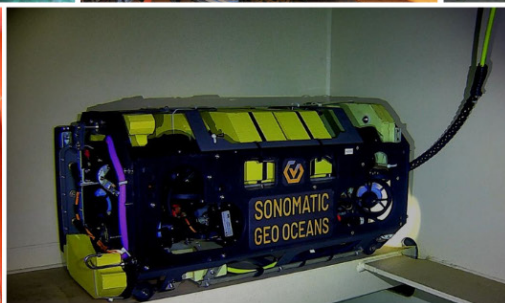
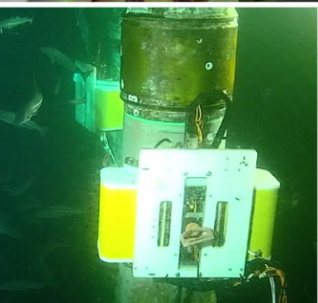
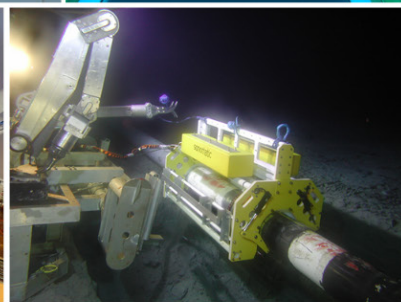
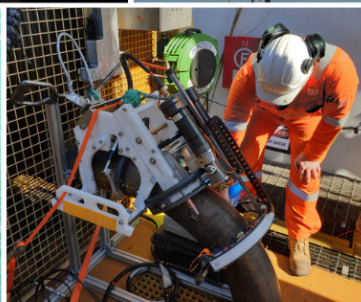
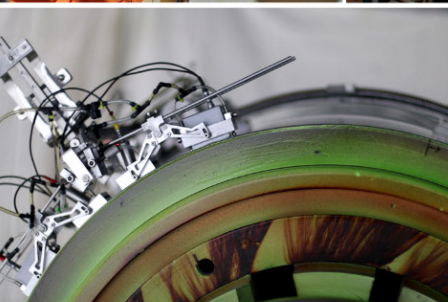
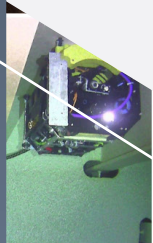
MEC-PIPESCANNER



SONOMATIC

THE PURPOSE

This document is composed to assist our clients and the supply chain with a high-level understanding of the benefits and services associated with our Pipeline and Riser Inspection capabilities using our MEC-Pipescanner.



PIPELINE & RISER INSPECTION

MEC-PIPESCANNER



The range of MEC-Pipescanners is designed and built for the high speed and high performance inspection of pipelines, risers and pressure vessels. Based on the Magnetic Eddy Current (MEC) technique which is the next generation and a further development of the fast corrosion mapping SLOFEC™ technique, the MEC-Pipescanners enable the detection of internal and external defects, including very small diameter and volume isolated internal pits with wall loss from 10% onwards.



The MEC technique is dynamic electromagnetic technique that operates on a high frequency Eddy Current field with a controlled direct current magnetic field and specially developed sensors to achieve a very high sensitivity in defect detection. The Eddy Current signal analysis within the multiple sensors enables not only the higher defect detection capability but also the direct sizing of topside and underside defects at a higher wall thickness and coating thickness range.



The MEC-Pipescanners provide clear distinction between internal and external defects. They are able to inspect carbon steel, stainless steel and duplex steel materials, including through non-magnetic coatings such as GRP, rubber and paint. Direct surface coupling is not necessary due to its electromagnetic principle. With its comprehensive reporting software, accurate, reliable, and repeatable inspection results are provided in real time. The advanced colour condition mapping report provides an analysis of both the detected external and internal defects in terms of size, wall loss severity and location.

KEY FEATURES & BENEFITS

- ✔ High defect detection sensitivity in pipes
 - with diameter ranging from 1" and above to flat surfaces
 - with wall thickness up to 31mm
 - coating thickness up to 12mm including splashtron
 - experience with temperatures up to 170 deg C
- ✔ High inspection speed of approx. 20m/min
- ✔ Average accuracy of +/- 10%
- ✔ Detection capability for internal and external defects from < 10% wall loss depending on wall thickness and defect size from Ø 3mm
- ✔ Ability to inspect different steel materials (carbon, stainless, duplex and super duplex)
- ✔ Ability to detect pitting, cracks and various types of corrosion like CO₂, microbiological and ammonium chloride salt corrosion, under deposit corrosion
- ✔ Ability to detect internal and external defects in both horizontal and vertical pipes and vessels
- ✔ Minimal surface preparation prior to inspection

TECHNICAL SPECIFICATIONS

	MEC-P9	MEC-P13	MEC-P19
GENERAL SPECIFICATIONS			
Dimensions (L x W x H) mm (without handgrips)	318 x 431 x 121 318 x 190 x 113	381 x 531 x 141 NA	427 x 293 x 189 427 x 217 x 124
Weight	11 kg	23 kg	33 kg
No. of Sensors	4	4	8
Sensor Width	22.4 mm	20 mm	18.7 mm
Scanning Width	90 mm	100 mm	150 mm
Typical Wall Thickness Range ^{*1}	0 -9 mm	0 -13 mm	0 -31 mm
Use for Diameter	from 1" - flat surface	from 4" - flat surface	from 4" - flat surface
Magnetisation Unit	Permanent Magnet System		Electromagnetic System
Packaging	3 Pelican Cases (22" x 24" x 15") total weight about 70kg		
SIGNAL CABLE			
Max. Cable Length ^{*2}	40 metres	40 metres	40 metres
Weight	0.3 kg/m	0.3 kg/m	0.3 kg/m
EDDY CURRENT UNIT, COMPUTER & POWER SUPPLY UNIT			
Electronic	EddyIQ 3.0 advanced multiple channel eddy current electronic system with power supply unit		
Computer	Industrial laptop system connected via TCP/IP port to electronic system station with laptop based separately and connected via the scanner umbilical		
TYPICAL FAR SIDE DEFECT DETECTION SENSITIVITY AT MID WT RANGE			
Typical Smallest Defect Size ^{*3}	~ Ø 3 - 5 mm	~ Ø 3 - 5 mm	~ Ø 3 - 5 mm
Typical Smallest Defect Depth ^{*4}	From 10% - 20%	From 10% - 20%	From 10% - 20%
Max. Stand-off / Coating	3 - 5 mm	4 - 6 mm	6 - 12 mm

*1: Refers to the typical wall thickness range of standard material; may vary depending on material quality.

*2: The length of cable is divided into sections of 20m; extended cable length available on request.

*3: Refers to possible detectability, depending on scanner stand-off, quality of material and general surface condition.

*4: Refers to possible detectability, depending on general surface condition.

ADVANTAGES OF MEC TECHNIQUE

The MEC technique is a dynamic electromagnetic technique that operates on high frequency magnetic field controlled Eddy Current in combination with specially developed sensors able to generate a higher density Eddy Current field. As a result, the MEC technique offers the following advantages over MFL.

Lower Direct Current Magnetic Field

The MEC technique generates a lower direct current magnetic field than MFL which enables the following:

- Higher wall thickness inspection
- Larger stand-off inspection
- Less influence from the inspection surface
- Higher detection of small and shallow defects on either side of the pipe or vessel surface

Higher Frequency Eddy Current

The high frequency Eddy Current that the MEC technique operates on offers the following advantages:

- Differentiating and mapping internal / external defects separately
- Discriminating defects and non-defect indications such as inclusions and laminations through the use of the signal phase
- Very low influence of the defect shape on the defect detection
- High defect detection sensitivity of > 3mm pits from 10% wall loss
 - With a POD of > 90% for defects $\varnothing > 5\text{mm}$ and > 20% wall loss
 - Accuracy of defect sizing of +/- 10% for onsite reporting and +/- 5% for special offline analysis

Direct Assessment of Detected Defects

The MEC technique enables the direct sizing of the defects without the need for Ultrasonic verification.

KEY CONTACTS

EUROPE AND AFRICA

Graham Marshall
Subsea Project Manager
T: +44 (0) 1224 823 960
E: Graham.Marshall@sonomatic.com

Mike Churchill
Technical Authority & Manager
T: +44 (0) 7442 614244
E: Michael.Churchill@sonomatic.com

Stuart Ley
Topside Project Manager
T: +44 (0) 1224 823 960
E: Stuart.Ley@sonomatic.com

Danielle Gunns
Project Delivery Manager (Warrington)
T: +44 (0) 1925 414 000
E: Danielle.Gunns@sonomatic.com

Charles Loader
General Manager - Europe & Africa
T: +44 (0) 1925 414 000 | M: +44 (0) 7376 714 765
E: Charles.Loader@sonomatic.com

MIDDLE EAST, CASPIAN & BLACK SEA

Clayton Webb
Regional Manager
T: +971 26 580 708
E: Clayton.Webb@sonomatic.com

AUSTRALASIA

Jonathan Millen
Operations Manager - Australia
T: +61 477 030 058
E: Jon.Millen@sonomatic.com.au

Alex Cesan
General Manager - Australia & NZ
T: +61 498 442 666
E: Alex.Cesan@sonomatic.com.au

Zach McCann
Region Manager - South East Asia
T: +60 361 581 185 / 1180
M: +60 12 555 1569 / +61 404 797 670
E: Zach.Mccann@sonomatic.com.my

AMERICAS

Esteban Cesan
President
T: +1 832 977 0303
E: Esteban.Cesan@sonomatic.com

Agata Surowiec Morgan
Vice President - Business Development
T: +1 832 316 9925
E: Agata.Surowiec@sonomatic.com

Alessandro Vagata
Subsea Robotics Project Manager
T: +1 832 318 3314
E: Alessandro.Vagata@sonomatic.com



www.sonomatic.com